

Strain Sensors

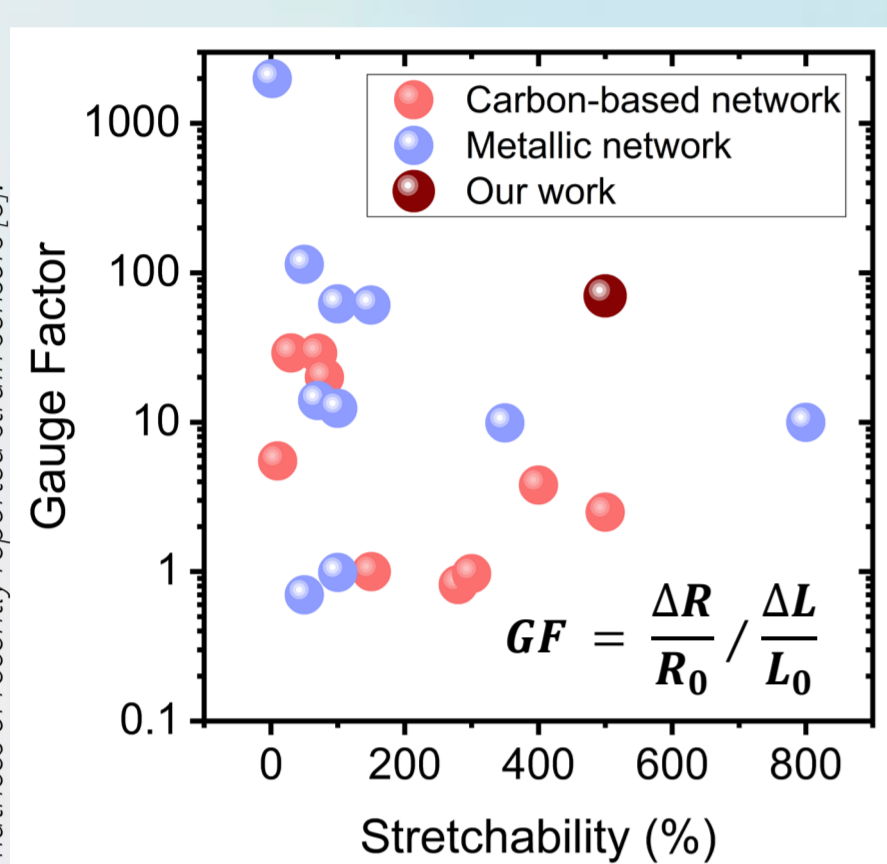
While strain sensors are the best approach to contact mode monitoring¹, it is difficult to find a compromise between their elasticity and sensitivity². These devices accurately detect deformation, triggering a shift on its resistivity. The fractional resistance change is related to the mechanical strain by the Gauge Factor (GF):



Fig. 2. Fabrication of graphene-coated silicone droplets.

The optimal choice of functional nanoscale fillers³⁻⁶ and elastic matrix²⁻⁶ (Fig. 1) makes the sensor easily tuneable according to the application and target⁴. In collaboration with NASA, I'm utilising liquid-exfoliated graphene nanosheets and commercially-available silicones to develop the next generation of nanocomposite strain sensors³ (Fig. 2), yielding excellent electro-mechanical properties with a robust exponential response to applied strain.

Fig. 1. Results of different combinations of fillers and matrices of recently reported strain sensors [5].



Experimental

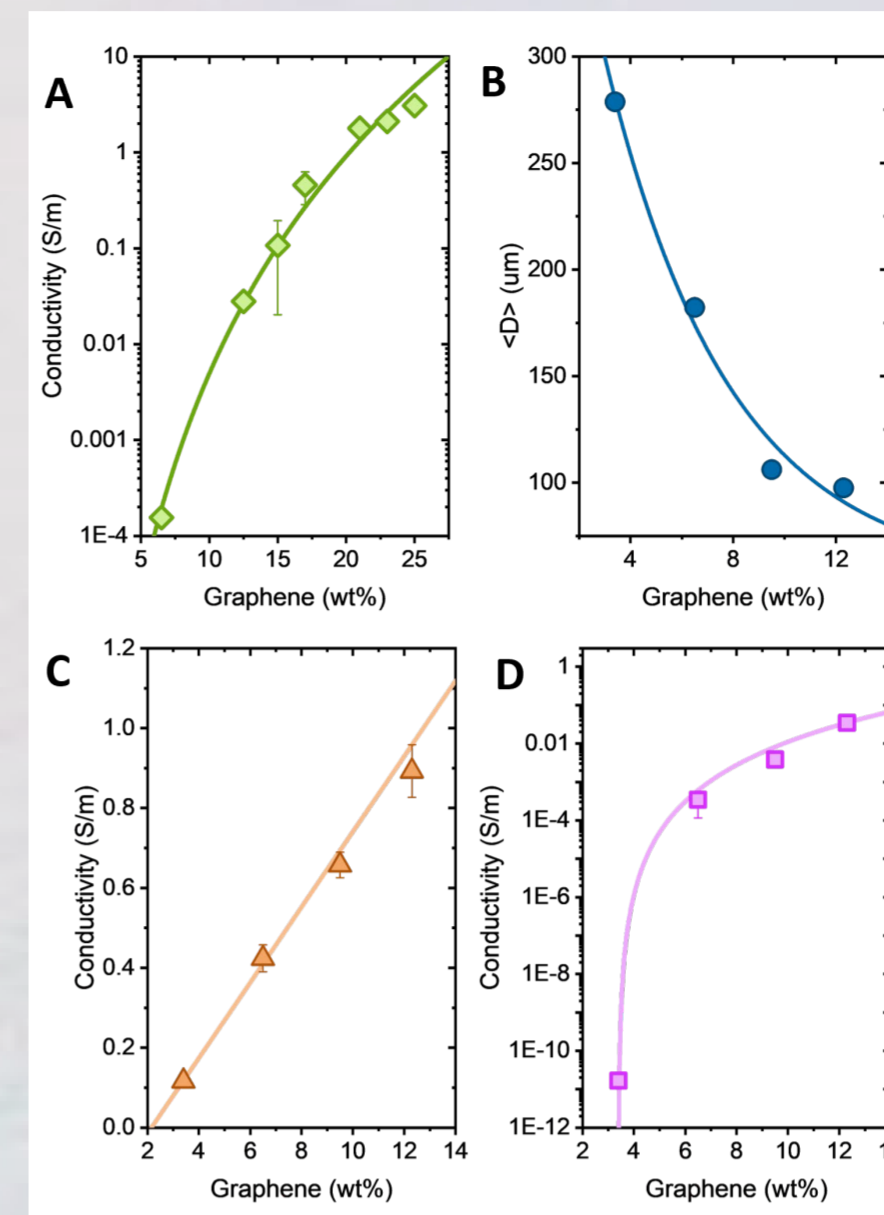


Fig. 3. Plots of the influence of graphene % on A) the conductivity of the matrix, B) the G-Balls diameter, C) the conductivity of the G-Balls, D) G-Balls on the conductivity of the filler.

The sensor properties (conductivity, G-Balls diameter, etc.) are easily tuneable by changing the graphene content (Fig. 3), allowing to choose the most suitable diameter. In a nutshell, the conductivity increases with the graphene concentration, however it introduces stiffness into the matrix.

As can be seen Fig. 4, the sensor is very versatile and can be easily attached to substrates of different nature (skin, nylon, Kevlar, metal, glass, etc.).

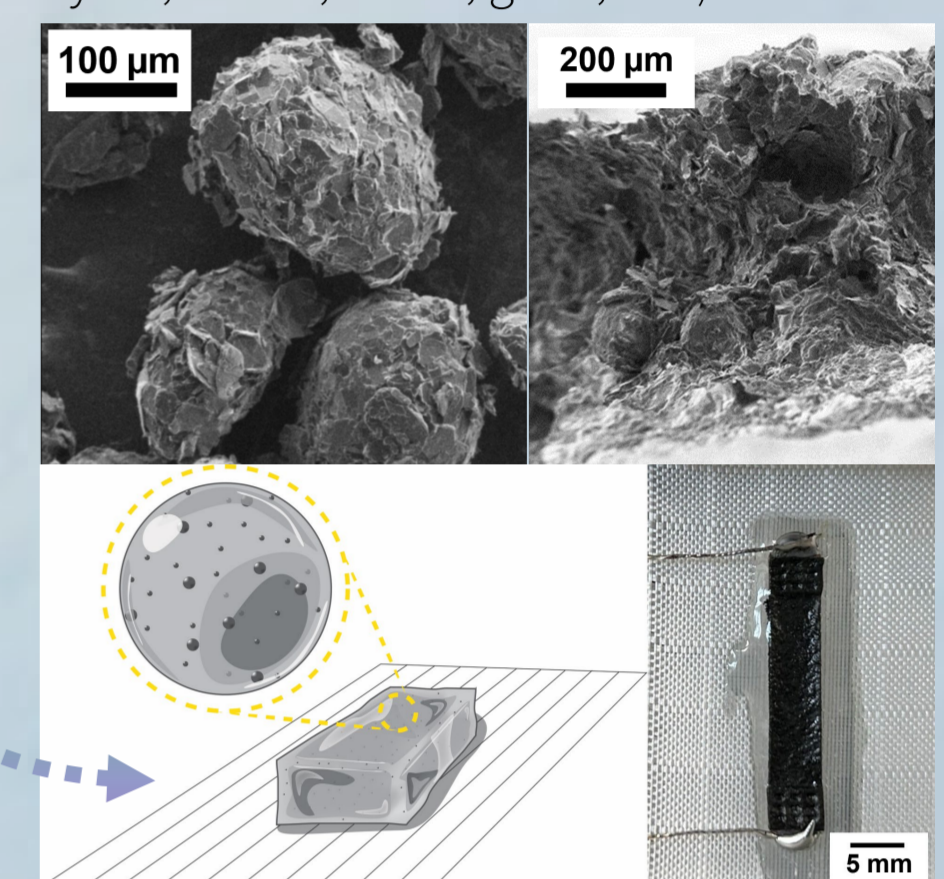


Fig. 4. Sensor SEM images and casting process and set up.

Research Aims

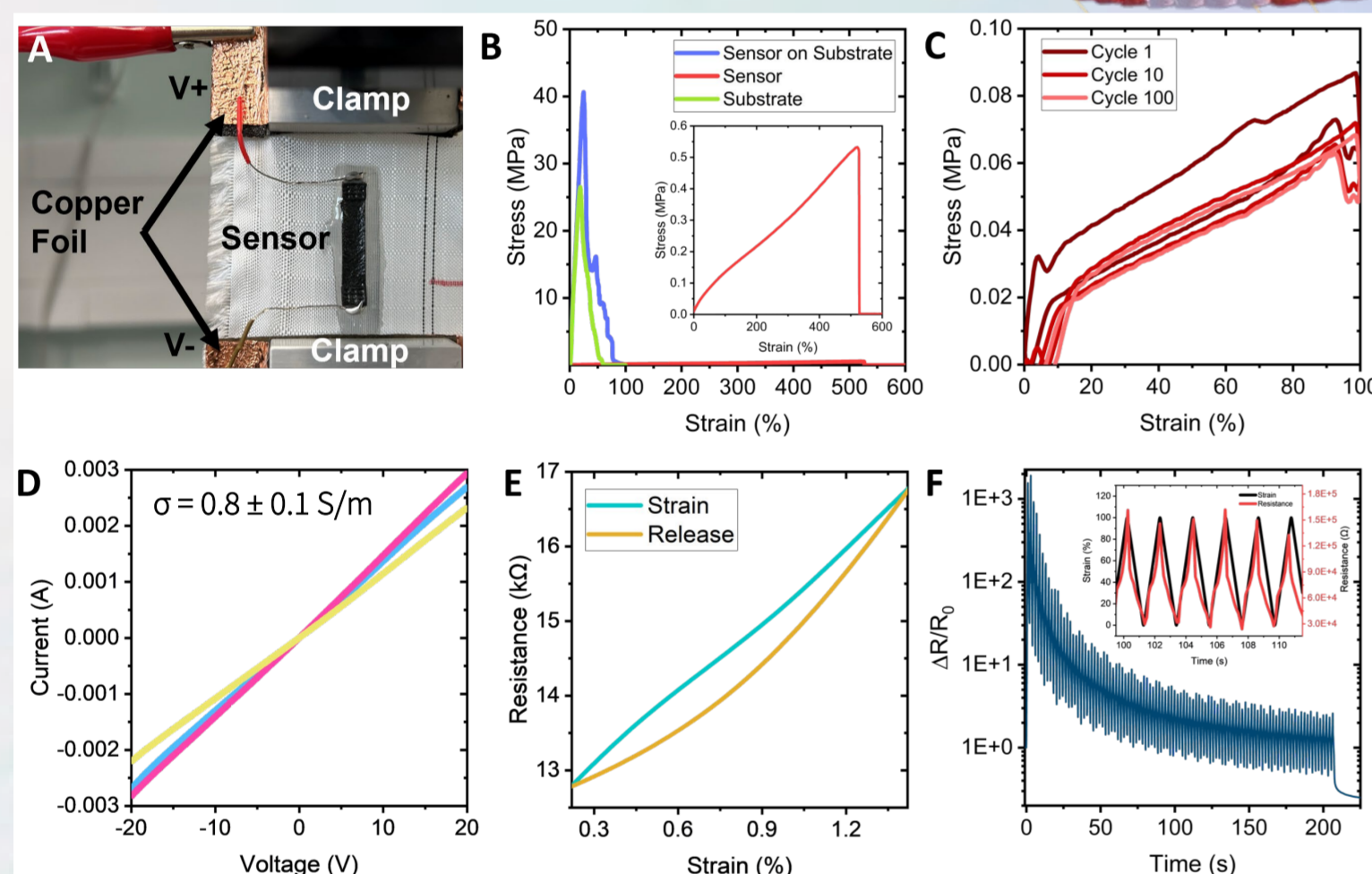


Fig. 5. A) Experimental configuration. B) Strain to break measurements. C) Hysteresis of the sensor. D) I-V characterisation. E) Resistance vs strain. F) Resistance change over 100 cycles.

We've observed no obvious damage after more than 500 cycles up to 100% strain and at a strain rate of 100% per second. Mechanical hysteresis is shown to decrease with increasing cycle number (almost identical in cycle 10 - 100). The sensor exhibits good ohmic conductivity. For the single, high strain rate strain to break measurement a well-defined

exponential response is observed up to 160% strain, featuring a high R/R_0 of 2×10^5 (Fig. 5). One of the aims of the project is to integrate and attach the sensor to surfaces of diverse nature. Here we've attached it to a nylon fabric that works as a parachute (Fig. 6A) canopy material provided by NASA.

Results & Discussion

The sensor presents a long durability and good recovery. As can be observed in Fig. 6B, for both configurations (free-standing GF = 59.5, on substrate GF = 60.1) the sensor has a very stable performance, showing no variation on the Gauge Factor when attached to different substrates, and no variability over 1000 cycles. The sensor presents good attachment and behaviour, and when comparing the Gauge Factor of both cases, it is remarkable that the substrate barely affect its value, showing reliability and versatility.

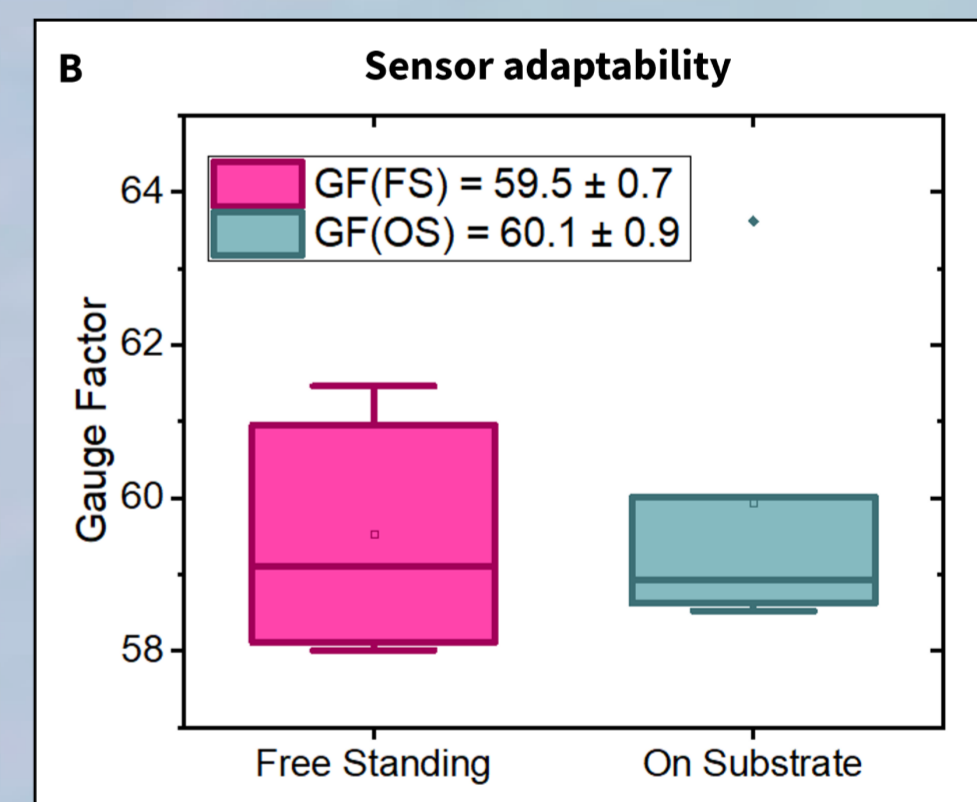
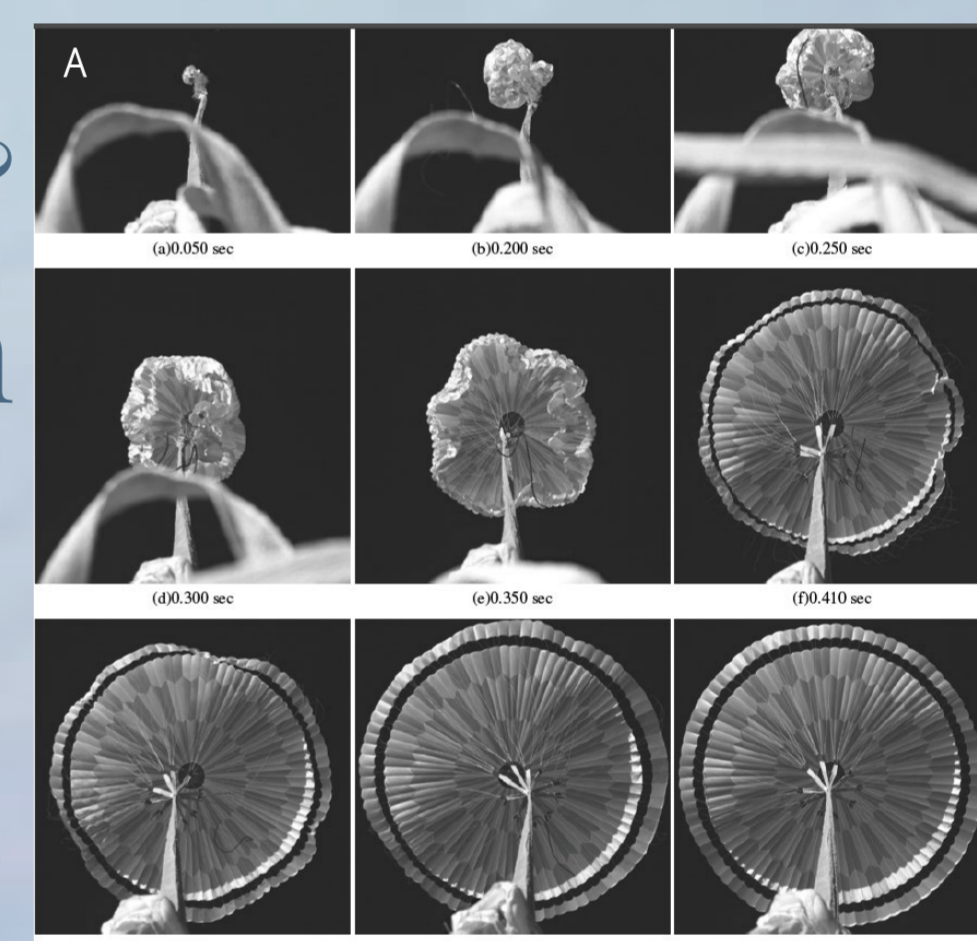
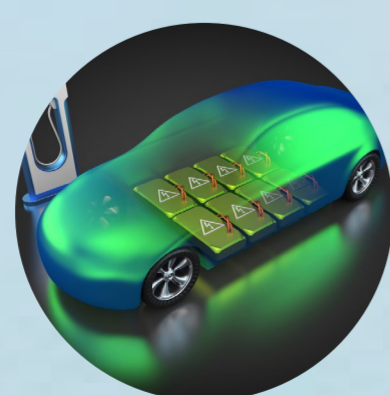


Fig. 6. A) NASA images of a canopy deployment. A) Free Standing sensor and Sensor on Canopy Gauge Factor up to 1000 cycles.

Applications & Sustainability



Monitoring of the loads experienced by wind turbine blades during operation and their deterioration (fatigue testing).



Strain is a critical parameter to determine the state of lithium-ion batteries, as it is an efficiency and safety indicator⁷.



Strain sensors have a broad range of health-related applications: breathing, pulse, swallowing and joint movements detection.

Conclusions

- We've developed an innovative, adaptable and integrable strain sensor made in Sussex.
- The sensor presents high sensitivity and good mechanical properties, making it competitive with the sensors in the literature.
- The versatility of the sensor makes it useful for health, aerospace and sustainability applications.

References

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